# ON THE EXTREMAL POINTS OF THE $\Lambda$-POLYTOPES AND CLASSICAL SIMULATION OF QUANTUM COMPUTATION WITH MAGIC STATES 

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#### Abstract

We investigate the $\Lambda$-polytopes, a convex-linear structure recently defined and applied to the classical simulation of quantum computation with magic states by sampling. There is one such polytope, $\Lambda_{n}$, for every number $n$ of qubits. We establish two properties of the family $\left\{\Lambda_{n}, n \in \mathbb{N}\right\}$, namely (i) Any extremal point (vertex) $A_{\alpha} \in \Lambda_{m}$ can be used to construct vertices in $\Lambda_{n}$, for all $n>m$. (ii) For vertices obtained through this mapping, the classical simulation of quantum computation with magic states can be efficiently reduced to the classical simulation based on the preimage $A_{\alpha}$. In addition, we describe a new class of vertices in $\Lambda_{2}$ which is outside the known classification. While the hardness of classical simulation remains an open problem for most extremal points of $\Lambda_{n}$, the above results extend efficient classical simulation of quantum computations beyond the presently known range.


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## 1 Introduction

The question of precisely which property of quantum mechanics is responsible for the speedup in quantum computation to date remains open. Various candidates have been put forward, such as superposition and interference [1] , entanglement [2,3], and largeness of Hilbert space [4], but there is always a counterexample that stops broad generalization; see e.g. [5- 8 ]. To identify new candidates, or perhaps even refine the question, one may study classical simulation algorithms for quantum systems, and specifically how the efficiency of such algorithms breaks down when pushed towards the regime of universal quantum computation.

The classical simulation method of present interest is based on sampling from the $\Lambda$ polytope [9]. Before turning to it, to provide context, we briefly discuss other classical simulation methods for quantum computation, and the general structure that unifies them.

Classical simulation techniques for quantum computation typically seek to exploit proximity to a simple, "effectively classical" reference point. The characteristic simplifying feature of such reference points varies; examples are locality [10], stabilizerness [5], matchgates 11, 12], and the positivity of Wigner functions 13,14 . Furthermore, often a natural measure exists for the distance between the setting of interest and the classical reference point. This can be, in case of locality as the simplifying feature, the bond dimension in MPS states 2], or the graph-theoretic measure of rankwidth in classical simulation of measurement based quantum computation on graph states [3]. If stabilizer-ness is the simplifying feature, measures of state magic 1320 such as Wigner function negativity or stabilizer rank quantify the hardness of classical simulation.

Irrespective of the concrete approach, these classical simulation methods share four general features: (i) A sector in which the classical simulation is efficient, (ii) a physical property that characterizes this sector, (iii) a physical property of universal quantum computation that obstructs efficiency of the simulation method in the general case, and (iv) a distance measure from the setting of interest to its closest efficiently simulable setting, governing the hardness of classical simulation.

In this paper, we are concerned with the recently introduced method of simulating quantum computation based on sampling from the $\Lambda$-polytope 9]. Being a sampling algorithm, it is closely related to the sampling algorithms invoking Wigner functions and other quasiprobability distributions $[13,15,21,24$. However, there is also an important difference: in the present method, no negativity ever occurs!

This prompts the question of where quantumness is hiding in this scenario. If quantumness cannot be attributed to negativity, then to what else? To summarize the state of knowledge about the classical simulation by sampling from the $\Lambda$-polytope 9 , of the above general characteristics (i) - (iv), we presently only have a glimpse of (i). Namely, it is known that in the subpolytope spanned by the so-called cnc vertices, classical simulation is efficient 24]; and this includes the domain of the stabilizer formalism [5] as a strict subset. But it is presently unknown how far the efficiently simulable region extends, which physical property this efficiency is to be attributed to, and which opposing physical property would render the simulation of the general case inefficient.

This paper is a first approach to the systematic study of the $\Lambda$-polytopes. We investigate the structure of the extremal points of the polytopes $\Lambda_{n}$ for any number $n$ of qubits, asking: Can the vertices of $\Lambda_{n}$ be constructed from smaller parts? And if so, can the classical simulation of quantum computation based on such vertices be reduced to the classical simulation of those parts? -Here, we give affirmative first answers to these questions, extending the classically efficiently simulable sector of the model [9].

The main results of this paper are:

- Theorem 2 (Section 3): For every vertex $X \in \Lambda_{m}$, every projector onto an $(n-m)$ qubit stabilizer state $|\sigma\rangle, \Pi_{\sigma}=|\sigma\rangle\langle\sigma|$, and every $n$-qubit Clifford unitary $U$, it holds that $U\left(X \otimes \Pi_{\sigma}\right) U^{\dagger}$ is a vertex of $\Lambda_{n}$.
- Theorem 3 (Section 4): The classical simulation of quantum computation with magic states $(\mathrm{QCM})$, with the $n$-qubit initial state $\tilde{X}=U\left(X \otimes \Pi_{\sigma}\right) U^{\dagger}$, can be efficiently reduced to the classical simulation of QCM with the $m$-qubit initial state $X$.
- Theorem 4 (Section 5): We describe a new family of vertices $X \in \Lambda_{2}$, i.e., of two qubits, which is outside the closed and noncontextual (cnc) classification [24. It is the first explicitly known family, including the update under Pauli measurements, beyond cnc.

The significance of the first result is that whenever we learn about a new vertex of $\Lambda_{m}$, it implies an infinite family of vertices on $n>m$ qubits. The second result means that, for the entire infinite family of vertices resulting from $X$, the hardness of classical simulation of QCM is essentially given by the hardness of simulating QCM on $X$. This result, together with the new class of efficiently updateable vertices provided by the third result, extends the efficiently classically simulable sector for the present method.

This paper is organized as follows. In Section 2 we review background material. We state the definition of the state polytopes $\Lambda_{n}$ and provide a motivation for studying them. In Section 3 we show how to construct vertices of the state polytope $\Lambda_{n}$ from vertices of the polytope $\Lambda_{m}$, for $n>m$. Section 4 is concerned with the efficiency of classical simulation of quantum computation with magic states. For the cases where a vertex under consideration is the result of the map defined by Theorem 2, we describe a reduction to the classical simulation of the preimage of the map. In Section 5, we describe a new family of two-qubit vertices that is outside the presently known cnc classification. We conclude in Section 6 .

## 2 Background

This section begins with a short summary of quantum computation with magic states (Section 2.11, which provides our main motivation for studying the $\Lambda$-polytopes. We then state the definition of the state polytopes $\Lambda_{n}$ and summarize the properties presently known of them (Section 2.2). We conclude with a discussion of the role of the tensor product for the present construction (Section 2.3).

### 2.1 Quantum computation with magic states

The $\Lambda$-polytopes have found a surprising application in describing universal quantum computation with magic states in terms of sampling 9 . Therefore, before we discuss the $\Lambda$-polytopes themselves we provide a brief summary of that scheme of quantum computation.

Quantum computation with magic states (QCM) 26-28 is a scheme for universal quantum computation, closely related to the circuit model. There is also an important difference. The unitary gates in QCM are not universal. This is compensated by the provision of so-called magic states which restore computational universality. In this way, computational power shifts from the gates to the initial states. As an aside, from a practical point of view QCM is very advantageous for fault-tolerant quantum computation 28 .

There are two types of operations in QCM, the "free" operations and the "resources". The free operations are (i) preparation of all stabilizer states, (ii) the Clifford unitaries, and (iii) measurement of all Pauli observables.

The resource are arbitrarily many copies of the state

$$
\begin{equation*}
|T\rangle=\frac{|0\rangle+e^{i \pi / 4}|1\rangle}{\sqrt{2}} \tag{1}
\end{equation*}
$$

The state $|T\rangle$ is called a "magic state", as it restores computational universality given the other above operations.

The distinction between free operations and resources in QCM is motivated by the GottesmanKnill theorem which says that free operations alone can be efficiently classically simulated.

### 2.2 The $\Lambda$-polytopes

### 2.2.1 Definition

Let $\operatorname{Herm}\left(2^{n}\right)$ denote the set of Hermitian operators on the $n$-qubit Hilbert space $\mathcal{H}=\mathbb{C}^{2^{n}}$. We recall the definition of the polytope $\Lambda_{n}$ from (9),29]:

$$
\begin{equation*}
\left.\Lambda_{n}=\left\{X \in \operatorname{Herm}_{1}\left(2^{n}\right)|\operatorname{Tr}(X|\sigma\rangle\langle\sigma|) \geq 0, \forall| \sigma\right\rangle \in \mathcal{S}_{n}\right\} \tag{2}
\end{equation*}
$$

where $\operatorname{Herm}_{1}\left(2^{n}\right) \subset \operatorname{Herm}\left(2^{n}\right)$ denotes the subset of Hermitian matrices of trace 1 and $\mathcal{S}_{n}$ denotes the set of pure $n$-qubit stabilizer states. The set of vertices of $\Lambda_{n}$ is denoted by $\left\{A_{\alpha} \mid \alpha \in \mathcal{V}_{n}\right\}$. We note that in 29] the polytope $\Lambda_{n}$ is used as a convenient tool to study the facets of the stabilizer polytope.

The state spaces $\Lambda_{n}$ are thus generalizations of the sets of proper density matrices. Namely, for density matrices we require that with respect to any quantum state, the Born rule yields a probability for finding that state in measurement, i.e., a nonnegative real number. For the elements of $\Lambda_{n}$, we relax this condition. Namely, we only require it for stabilizer states.

In what follows, we will often expand vertex operators in the basis of $n$-qubit Pauli operators. Writing $E_{n}$ for the vector space $\left(\mathbb{Z}_{2}\right)^{n} \times\left(\mathbb{Z}_{2}\right)^{n}$, the Pauli operators are

$$
T_{v}=i^{v_{Z} \cdot v_{X}} Z\left(v_{Z}\right) X\left(v_{X}\right), \quad \forall\left(v_{Z}, v_{X}\right)=v \in E_{n}
$$

where $v_{Z} \cdot v_{X}$ is computed mod 2 , and $X\left(v_{X}\right):=\bigotimes_{i=1}^{n}\left(X_{i}\right)^{\left[v_{X}\right]_{i}}, Z\left(v_{Z}\right):=\bigotimes_{i=1}^{n}\left(Z_{i}\right)^{\left[v_{Z}\right]_{i}}$. Sometimes we will write $T_{v}^{(n)}$ to emphasize that the operator is an $n$-qubit Pauli operator.
$E_{n}$ comes with a symplectic form defined by

$$
[v, w]=v_{Z}^{T} w_{X}+v_{X}^{T} w_{Z}
$$

for all $v=\left(v_{Z}, v_{X}\right), w=\left(w_{Z}, w_{X}\right) \in E_{n}$. We denote the canonical symplectic basis of $E_{n}$ by $\left\{x_{1}, \cdots, x_{n}, z_{1}, \cdots, z_{n}\right\}$. Also it is convenient to introduce the notation $y_{n}=x_{n}+z_{n}$. We write $\mathrm{Sp}_{2 n}\left(\mathbb{Z}_{2}\right)$ for the group of symplectic transformations acting on $E_{n}$. For a subspace $W \subset E_{n}$ let $W^{\perp}$ denote the subspace $\left\{v \in E_{n} \mid[v, w]=0, \forall w \in W\right\}$. A subspace $J \subset E_{n}$ is called isotropic if $J \subset J^{\perp}$. The collection of maximal isotropic subspaces of $E_{n}$ is denoted by $\mathcal{I}\left(E_{n}\right)$.

### 2.2.2 Properties of $\Lambda_{n}$

Beyond the defining relations and the application to QCM [9] to date two general structural facts are known about the family $\left\{\Lambda_{n}, n \in \mathbb{N}\right\}$ of state spaces. They are

1. For all $n, \Lambda_{n}$ is a polytope, hence it is bounded and the set of its extremal points is finite.
2. For all $n, \Lambda_{n}$ contains all $n$-qubit density matrices, and it maps into itself under conjugation by Clifford unitaries and Pauli measurements.


#### Abstract

Absence of negativity. As a consequence of the above point 2, negativity of quasiprobability distributions can be entirely dispensed with in the description of QCM. There exists a representation [9] for which all quantum states, as well as all quantum operations necessary for QCM, can be represented by probabilities and conditional probabilities, respectively, giving rise to a hidden variable model (HVM) describing universal quantum computation by sampling.

Namely, we have the following result invoking the state polytopes $\Lambda_{n}$ of Eq. (2). Theorem 1 ( $[\mathbf{9 ]})$ For all numbers of qubits $n \in \mathbb{N}$, (i) Each n-qubit quantum state $\rho$ can be represented by a probability function $p_{\rho}: \mathcal{V}_{n} \rightarrow \mathbb{R}_{\geq 0}$, $\rho=\sum_{\alpha \in \mathcal{V}_{n}} p_{\rho}(\alpha) A_{\alpha}$.


(ii) For the state update under Pauli measurements it holds that

$$
\Pi_{a, s} A_{\alpha} \Pi_{a, s}=\sum_{\beta \in \mathcal{V}_{n}} q_{\alpha, a}(\beta, s) A_{\beta}
$$

For all $a \in E_{n}, \alpha \in \mathcal{V}_{n}$, the $q_{\alpha, a}: \mathcal{V}_{n} \times \mathbb{Z}_{2} \rightarrow \mathbb{R}_{\geq 0}$ are probability functions,
(iii) Denote by $P_{\rho, a}(s)$ the probability of obtaining outcome $s$ for a measurement of $T_{a}$ on the state $\rho$. Then, the Born rule $P_{\rho, a}(s)=\operatorname{Tr}\left(\Pi_{a, s} \rho\right)$ takes the form

$$
\operatorname{Tr}\left(\Pi_{a, s} \rho\right)=\sum_{\alpha \in \mathcal{V}_{n}} p_{\rho}(\alpha) Q_{a}(s \mid \alpha)
$$

Therein, $Q_{a}(s \mid \alpha)$ is given by $Q_{a}(s \mid \alpha):=\sum_{\beta \in \mathcal{V}_{n}} q_{\alpha, a}(\beta, s)$. Hence $0 \leq Q_{a}(s \mid \alpha) \leq 1$, for all $a, s, \alpha$.

The above Theorem 1, and its application to the classical simulation of quantum computation with magic states, is our main motivation for studying the polytopes $\Lambda_{n}$. The theorem does not speak about the Clifford gates; however, those are also positively represented (see the SM of 9 , Sec. I). Alternatively, the Clifford gates may be propagated past the last measurement in any given QCM circuit, and then discarded. They do not add computational power beyond that afforded by the Pauli measurements 32].

Cnc vertices. There is an infinite family of vertices of the $\Lambda$-polytopes, the so-called cnc vertices, which is completely understood. Any cnc vertex in $\mathcal{V}_{n}$ has the form

$$
\begin{equation*}
A_{\Omega}^{\gamma}=\frac{1}{2^{n}} \sum_{v \in \Omega}(-1)^{\gamma(v)} T_{v} \tag{3}
\end{equation*}
$$

where $\Omega \subset E_{n}$ is a maximal cnc set, to be defined below. The set of $n$-qubit cnc-type vertices are denoted by $\mathcal{V}_{n}^{\text {cnc }}$.
"Cnc" in 'cnc set $\Omega$ ' stands for "closed noncontextual", and means the following. (Closure) A set $\Omega \subset E_{n}$ is closed if $v, w \in \Omega$ and $[v, w]=0$ implies that $v+w \in \Omega$. (Noncontextuality) $\Omega$ admits a consistent noncontextual value assignment $\gamma: \Omega \longrightarrow \mathbb{Z}_{2}$. That is, the eigenvalue found in the measurement of the Pauli observable $T_{v}$ is $(-1)^{\gamma(v)}$. The consistency requirement
is that for a triple of commuting Pauli observables $T_{v}, T_{w}, T_{v+w}$, with $T_{v+w}=(-1)^{\beta(v, w)} T_{v} T_{w}$, it holds that $\gamma(v+w)=\gamma(v)+\gamma(w)+\beta(v, w) \bmod 2$.

The reason for imposing the consistency condition is that if the three observables $T_{v}, T_{w}$, $T_{v+w}$ are simultaneously measured, on any quantum state, then the measurement outcomes of these observables satisfy the above constraint with certainty. Hence we require the same of all considered value assignments $\gamma$. The consistency condition also explains the need for the closure property. If $v, w \in \Omega$ then the expectation values for $T_{v}, T_{w}$ are extremal. The expectation value for $T_{v+w}$ must then also be extremal, hence we require $v+w \in \Omega$ for $A_{\Omega}^{\gamma}$ to reproduce this.

The following is known about the cnc vertices:

1. For any $n \in \mathbb{N}$, the convex hull of $\mathcal{V}_{n}^{\mathrm{cnc}}$ is closed under Pauli measurement. That is, for any projector $\Pi_{a, s}$ onto the eigenspace of $T_{a}$ corresponding to the eigenvalue $(-1)^{s}$ it holds that if $\operatorname{Tr}\left(\Pi_{a, s} A_{\Omega}^{\gamma}\right)>0$ then $\Pi_{a, s} A_{\Omega}^{\gamma} \Pi_{a, s}$ is a probabilistic linear combination of cnc vertices (Theorem 2 of 24 .)
2. The update of the pair $(\Omega, \gamma)$ under Pauli measurement is computationally efficient (Theorem 3 of 24 ).
3. The phase point operators $A_{\Omega}^{\gamma}$ are extreme points of the respective polytopes $\Lambda_{n}$ [9, 29].
4. The cnc sets $\Omega$ are classified for all $n \in \mathbb{N}$ (Theorem 1 of 24 ; also see Theorem 2 of [25]).

Item 3 provides an element of continuity between the simulation method 9 of present interest and the earlier simulation schemes based on Wigner functions 13, 23, 24. Namely, the phase point operators $A_{\Omega}^{\gamma}$ were initially devised for a classical simulation scheme 24] of quantum computation with magic states in which negativity can arise. The latter is the multiqubit counterpart to the initial work on the role of Wigner function negativity for quantum computation [13], which applies only to odd Hilbert space dimension.

Duality. Each polytope $\Lambda_{n}$ is the polar dual of the $n$-qubit stabilizer polytope $\mathcal{O}_{n}$ 29. Therefore, every vertex of $\Lambda_{n}$, for any $n \in \mathbb{N}$, corresponds to a linear inequality that bounds $\mathcal{O}_{n}$.

This has an implication for $n=2$. Namely, the linear inequalities bounding $\mathcal{O}_{2}$ have been described in 33], see Table II and Eq. (22) therein. This immediately provides a classification of the vertices of $\Lambda_{2}$.

The vertex enumeration problem, namely the problem of computing the vertices of a polytope given a description as the intersection of the set of halfspaces, is a fundamental problem in computational geometry. Algorithms exist for this problem (e.g. lrslib 35] and cddlib [36]) with computational complexity which typically depends on the input size (the number of bounding halfspace inequalities), the output size (the number of vertices), and the dimension of the space. In our case, the dimension of the space $\operatorname{Herm}_{1}\left(2^{n}\right)$ grows exponentially with the number $n$ of qubits, and the input size grows like $2^{[1 / 2+o(1)] n^{2}} 37$. This makes numerical computation of the vertices of $\Lambda_{n}$ difficult even for small $n$.

So far a complete enumeration has only been possible for up to $n=2$ [33]. There are 60 bounding inequalities of $\Lambda_{2}$ and 22320 vertices of $\Lambda_{2}$ which fall into 8 orbits under the action of the Clifford group.

It is possible that the Clifford group symmetry of $\Lambda_{n}$ could be used to reduce the vertex enumeration problem to the problem of enumerating a representative vertex from each Clifford orbit 38. It is unknown to the authors whether this reduction is sufficient to enumerate the vertices of $\Lambda_{n}$ for $n \geq 3$.

### 2.3 Status of the tensor product

Given two extremal points $A_{\alpha} \in \Lambda_{n}$ and $A_{\beta} \in \Lambda_{m}$, is the tensor product $A_{\alpha} \otimes A_{\beta}$ an extremal point of $\Lambda_{n+m}$ ?-This is not generally the case; in fact, $A_{\alpha} \otimes A_{\beta}$ may not even be contained in $\Lambda_{n}$. We can show this by example. Consider the one-qubit vertex 9

$$
A_{0}=\frac{I+X+Y+Z}{2}
$$

Then it holds that $A_{0} \otimes A_{0} \notin \Lambda_{2}$. To see this, consider the stabilizer (Bell) state $\left|B_{11}\right\rangle$ defined by the stabilizer relations $Z_{1} \otimes Z_{2}\left|B_{11}\right\rangle=-\left|B_{11}\right\rangle, X_{1} \otimes X_{2}\left|B_{11}\right\rangle=-\left|B_{11}\right\rangle$. With these relations, $\left\langle B_{11}\right| A_{0} \otimes A_{0}\left|B_{11}\right\rangle=-1 / 2$. Hence, with Eq. $2, A_{0} \otimes A_{0} \notin \Lambda_{2}$. In the terminology of the Pusey-Barrett-Rudolph (PBR) theorem [30], the HVM of Theorem 1 does not satisfy the condition of "preparation independence", thereby evading the consequences of the PBR theorem.

From the above discussion it appears that the tensor product does not play a particular role in the HVM described by Theorem 1. Or does it?

## 3 Mapping vertices of $\Lambda_{m}$ to $\Lambda_{n}$

In the introduction we asked whether the extremal points of the state polytopes $\Lambda_{n}$ can be constructed from smaller parts, and Section 2.3 concluded with the question of whether there is any significant role for the tensor product in the present formalism. It turns out that the two questions are related through a common answer.

In this section we construct a map $\Lambda_{m} \rightarrow \Lambda_{n}$, for any $m<n$, that sends a vertex of $\Lambda_{m}$ to a vertex of $\Lambda_{n}$. Moreover, under this map $\mathcal{V}_{m}$ maps injectively into $\mathcal{V}_{n}$. For the statement of our result we recall the definition of stabilizer projectors. Let $\Pi_{J, s}$ denote the projector corresponding to the pair $(J, s)$ consisting of an isotropic subspace $J \subset E_{n}$ and a value assignment $s: J \rightarrow \mathbb{Z}_{2}$. It has the form

$$
\Pi_{J, s}=\frac{1}{|J|} \sum_{v \in J}(-1)^{s(v)} T_{v}
$$

where $\|$ denotes the number of elements. For each stabilizer state $|\sigma\rangle \in \mathcal{S}_{n}$ the projector $\Pi_{\sigma}=|\sigma\rangle\langle\sigma|$ can be uniquely written as a projector of the form $\Pi_{I, s}$ for some maximal isotropic subspace $I \subset E_{n}$ and a value assignment $s: I \rightarrow \mathbb{Z}_{2}$.
Theorem 2 Let $J \subset E_{n}$ be an isotropic subspace of dimension $d=n-m$ and $S \in S p_{2 n}\left(\mathbb{Z}_{2}\right)$ such that $S\left(J_{0}\right)=J$ where $J_{0}=\left\langle x_{m+1}, \cdots, x_{n}\right\rangle$. Given value assignments $r_{0}: J_{0} \rightarrow \mathbb{Z}_{2}$ and $r: J \rightarrow \mathbb{Z}_{2}$ define a linear map

$$
\Phi_{J, r}: \operatorname{Herm}\left(2^{m}\right) \rightarrow \operatorname{Herm}\left(2^{n}\right)
$$

by the formula

$$
\begin{equation*}
\Phi_{J, r}(X)=U\left(X \otimes \Pi_{J_{0}, r_{0}}\right) U^{\dagger} \tag{4}
\end{equation*}
$$

where $U$ is a Clifford unitary that implements $S$ and satisfies $U \Pi_{J_{0}, r_{0}} U^{\dagger}=\Pi_{J, r}$. Then the map $\Phi_{J, r}$ satisfies the following properties:

1. The image of $\Phi_{J, r}$ is given by $\left\{\left(\Pi_{J, r} Y \Pi_{J, r}\right) / \operatorname{Tr}\left(Y \Pi_{J, r}\right) \mid Y \in \Lambda_{n}\right.$ and $\left.\operatorname{Tr}\left(Y \Pi_{J, r}\right) \neq 0\right\}$.
2. $\Phi_{J, r}$ is injective and maps a vertex $X \in \Lambda_{m}$ to a vertex of $\Lambda_{n}$.
3. A vertex $X$ is of cnc-type (see Eq. (3)) if and only if $\Phi_{J, r}(X)$ is of cnc-type.

Presently, very little is known about the vertices of the polytopes $\Lambda_{n}$, for $n \geq 3$; and Theorem 2 extends that knowledge base. Essentially, the only fact already known is that the cnc construction 24 provides vertices of $\Lambda_{n}$ for all $n$. Cnc vertices have the property that they consist of a core tensored with a stabilizer tail, cf. Lemma 11 in 24]. Therein, the cores are related to Majorana fermions and the Jordan-Wigner transformation. Now, Theorem 2 establishes that all vertices of $\Lambda_{n}$, for any $n$, have the same overall structure: they consist of a core tensored with a stabilizer tail.

We now prepare for the proof of Theorem 2. We first consider the case $(J, r)=\left(J_{0}, r_{0}\right)$ so that $S$ is the identity matrix, and also the Clifford unitary $U$ is chosen to be the identity matrix. For $X \in \operatorname{Herm}\left(2^{m}\right)$ we can write

$$
X=\frac{1}{2^{m}} \sum_{v \in E_{m}} \alpha_{v} T_{v}^{(m)}
$$

and Eq. (4) implies that

$$
\begin{equation*}
\Phi_{J, r}(X)=X \otimes \Pi_{J, r}=\frac{1}{2^{n}} \sum_{v+u \in E_{m}+J}(-1)^{r(u)} \alpha_{v} T_{v+u}^{(n)} . \tag{5}
\end{equation*}
$$

The first step is to show that $\Phi_{J, r}$ maps $\Lambda_{m}$ into $\Lambda_{n}$. Given a value assignment $s: I \rightarrow \mathbb{Z}_{2}$ and a subspace $J \subset E_{n}$ we write $\left.s\right|_{I \cap J}$ for the restriction of $s$ to the intersection $I \cap J$. Given another value assignment $s^{\prime}: I \rightarrow \mathbb{Z}_{2}$ the delta function $\delta_{s^{\prime}, s}$ takes the value 1 if $s^{\prime}=s$ as functions on $I$ and 0 otherwise.

Lemma 1 Let I be a maximal isotropic subspace of $E_{n}$. Then

$$
\operatorname{Tr}\left(\Phi_{J, r}(X) \Pi_{I, s}\right)=\delta_{\left.r\right|_{K \cap J}, s \mid K \cap J} \frac{|K|}{2^{n}} \operatorname{Tr}\left(X \Pi_{K \cap E_{m},\left.s\right|_{K \cap E_{m}}}\right)
$$

where $K=\left(E_{m}+J\right) \cap I$. In particular, if $X \in \Lambda_{m}$ then $\Phi_{J, r}(X) \in \Lambda_{n}$.

Proof of Lemma 1. We have $\operatorname{Tr}\left(\Phi_{J, r}(X)\right)=1$ since $\operatorname{Tr}(X)=1$. We calculate

$$
\begin{aligned}
\operatorname{Tr}\left(\Phi_{J, r}(X) \Pi_{I, s}\right) & =\frac{1}{2^{n}} \sum_{v+u \in E_{m}+J}(-1)^{r(u)} \alpha_{v} \operatorname{Tr}\left(T_{v+u} \Pi_{I, s}\right) \\
& =\frac{1}{2^{n}} \sum_{v+u \in E_{m}+J}(-1)^{r(u)} \alpha_{v} \frac{1}{|I|} \sum_{w \in I}(-1)^{s(w)} \operatorname{Tr}\left(T_{v+u} T_{w}\right) \\
& =\frac{1}{2^{n}} \sum_{v+u \in\left(E_{m}+J\right) \cap I}(-1)^{r(u)} \alpha_{v}(-1)^{s(v+w)} \\
& =\frac{|K \cap J|}{2^{n}} \sum_{v \in K \cap E_{m}} \alpha_{v}(-1)^{s(v)}\left(\frac{1}{|K \cap J|} \sum_{u \in K \cap J}(-1)^{r(u)}(-1)^{s(u)}\right) \\
& =\delta_{\left.r\right|_{K \cap J},\left.s\right|_{K \cap J}} \frac{|K \cap J|}{2^{n}} \sum_{v \in K \cap E_{m}} \alpha_{v}(-1)^{s(v)} \\
& =\delta_{\left.r\right|_{K \cap J},\left.s\right|_{K \cap J}} \frac{|K \cap J|\left|K \cap E_{m}\right|^{2}}{2^{n}} \operatorname{Tr}\left(X \Pi_{K \cap E_{m},\left.s\right|_{K \cap E_{m}}}\right) \\
& =\delta_{\left.r\right|_{K \cap J},\left.s\right|_{K \cap J}} \frac{|K|}{2^{n}} \operatorname{Tr}\left(X \Pi_{K \cap E_{m},\left.s\right|_{K \cap E_{m}}}\right) \geq 0 .
\end{aligned}
$$

As a consequence of this calculation and the definition of $\Lambda_{n}$ the image $\Phi_{J, r}(X)$ belongs to $\Lambda_{n}$ for any $X \in \Lambda_{m}$.

Next we show that if $X \in \Lambda_{m}$ is a vertex then $\Phi_{J, r}(X)$ is a vertex of $\Lambda_{n}$. To achieve this we will use the following characterization of vertices of a polytope:

Let $P$ be a polytope in $\mathbb{R}^{N}$. Then a point $p \in P$ is a vertex if and only if there exists no non-zero $x \in \mathbb{R}^{N}$ such that $p \pm x \in P$ [31, page 18].

Our polytope $\Lambda_{n}$ lives inside $\operatorname{Herm}_{1}\left(2^{n}\right)$ and we can identify $\operatorname{Herm}_{1}\left(2^{n}\right)$ with $\mathbb{R}^{2^{2 n}-1}$ by choosing $\mathbb{1}_{2^{n}} / 2^{n}$ to be the origin. Therefore to prove that $\Phi_{J, r}(X) \in \Lambda_{n}$ is a vertex we need to show that $\left\{\Phi_{J, r}(X) \pm Y\right\} \not \subset \Lambda_{n}$ for any $Y \in \operatorname{Herm}\left(2^{n}\right)$ of trace zero. Let us write

$$
Y=\frac{1}{2^{n}} \sum_{0 \neq v \in E_{n}} \beta_{v} T_{v}^{(n)}
$$

and define another trace zero operator

$$
\begin{equation*}
\tilde{Y}=\frac{1}{2^{m}} \sum_{0 \neq v \in E_{m}} \tilde{\beta}_{v} T_{v}^{(m)} \tag{6}
\end{equation*}
$$

The coefficients $\tilde{\beta}_{v}$ are given by $\operatorname{Tr}\left(Y_{v} \Pi_{J, r}\right)$ where $Y_{v}=1 / 2^{n} \sum_{u \in J} \beta_{u+v} T_{u}^{(n)} \in \operatorname{Herm}\left(2^{n}\right)$. Furthermore, we have the relation

$$
\begin{equation*}
\tilde{\beta}_{v}=\frac{1}{|J|} \sum_{u \in J} \beta_{u+v}(-1)^{r(u)} \tag{7}
\end{equation*}
$$

Lemma 2 Let $I^{\prime} \subset E_{m}$ be a maximal isotropic subspace and $s^{\prime}: I^{\prime} \rightarrow \mathbb{Z}_{2}$ be a value assignment. Then

$$
\begin{equation*}
\operatorname{Tr}\left(Y \Pi_{J+I^{\prime}, r * s^{\prime}}\right)=\operatorname{Tr}\left(\tilde{Y} \Pi_{I^{\prime}, s^{\prime}}\right) \tag{8}
\end{equation*}
$$

where $r * s^{\prime}:\left(J+I^{\prime}\right) \rightarrow \mathbb{Z}_{2}$ is the value assignment defined by $r * s^{\prime}(u+v)=r(u)+s^{\prime}(v)$.

Proof of Lemma 2. We calculate

$$
\begin{aligned}
\operatorname{Tr}\left(Y \Pi_{J+I^{\prime}, r * s^{\prime}}\right) & =\frac{1}{|J|\left|I^{\prime}\right|} \sum_{v \in I^{\prime}} \sum_{u \in J} \beta_{u+v}(-1)^{r(u)+s(v)} \\
& =\frac{1}{\left|I^{\prime}\right|} \sum_{v \in I^{\prime}}(-1)^{s(v)} \frac{1}{|J|} \sum_{u \in J} \beta_{u+v}(-1)^{r(u)} \\
& =\frac{1}{\left|I^{\prime}\right|} \sum_{v \in I^{\prime}}(-1)^{s(v)} \tilde{\beta}_{v} \\
& =\operatorname{Tr}\left(\tilde{Y} \Pi_{I^{\prime}, s^{\prime}}\right) .
\end{aligned}
$$

For the third equality we use Eq. (7).
We are now ready to give a proof of our main result, Theorem 2
Proof of Theorem 2. We begin by proving Theorem 2 for $(J, r)=\left(J_{0}, r_{0}\right)$ in which case the map is given by Eq. (5). Part (1) follows immediately from comparing $\Pi_{J_{0}, r_{0}} Y \Pi_{J_{0}, r_{0}}$ after normalization with Eq. (5). For part (2) note that Lemma 1 says that $\Phi_{J, r}\left(\Lambda_{m}\right) \subset \Lambda_{n}$. Let $X$ be a vertex of $\Lambda_{m}$. We will show that $\left\{\Phi_{J, r}(X) \pm Y\right\} \not \subset \Lambda_{n}$ for any $Y \in \operatorname{Herm}\left(2^{n}\right)$ of trace zero. Since $X$ is a vertex either $X+\tilde{Y}$ or $X-\tilde{Y}$ lies outside of $\Lambda_{m}$, where $\tilde{Y} \in \operatorname{Herm}\left(2^{m}\right)$ is defined in Eq. (6). WLOG assume that $X+\tilde{Y} \notin \Lambda_{m}$. This means that there is a pair $\left(I^{\prime}, s^{\prime}\right)$ such that $\operatorname{Tr}\left((X+\tilde{Y}) \Pi_{I^{\prime}, s^{\prime}}\right)<0$. Lemma 1 with $I=J+I^{\prime}$ and $s=r * s^{\prime}$ gives

$$
\begin{equation*}
\operatorname{Tr}\left(\Phi_{J, r}(X) \Pi_{J+I^{\prime}, r * s^{\prime}}\right)=\operatorname{Tr}\left(X \Pi_{I^{\prime}, s^{\prime}}\right) \tag{9}
\end{equation*}
$$

Using Eq. (9) and Eq. (6) we obtain

$$
\operatorname{Tr}\left(\left(\Phi_{J, r}(X)+Y\right) \Pi_{J+I^{\prime}, r * s^{\prime}}\right)=\operatorname{Tr}\left((X+\tilde{Y}) \Pi_{I^{\prime}, s^{\prime}}\right)<0
$$

thus $X+Y$ lies outside of $\Lambda_{n}$. This completes the proof of part (2). Next we prove part (3). If $X=A_{\Omega}^{\gamma}$ for some cnc set $(\Omega, \gamma)$ where $\Omega \subset E_{m}$ then Eq. (5) implies that

$$
\Phi_{J, r}\left(A_{\Omega}^{\gamma}\right)=\frac{1}{2^{n}} \sum_{u+v \in J+E_{m}}(-1)^{r(u)+\gamma(v)} T_{u+v}=A_{J+\Omega}^{r * \gamma}
$$

Therefore we obtain a vertex of cnc-type. Conversely, if $\Phi_{J, r}(X)$ is a vertex of cnc-type given by $A_{\tilde{\Omega}}^{\tilde{\gamma}}$ for some cnc set $(\tilde{\Omega}, \tilde{\gamma})$ then again from Eq. (5) we see that $X=A_{\Omega}^{\gamma}$ where $\Omega=\tilde{\Omega} \cap E_{m}$ and $\gamma$ is given by the restriction $\left.\tilde{\gamma}\right|_{\Omega}$.

For the general case let $J \subset E_{n}$ be an arbitrary isotropic subspace and $r: J \rightarrow \mathbb{Z}_{2}$ be a value assignment. We will write $J_{0}$ for $\left\langle x_{m+1}, \cdots, x_{n}\right\rangle$ and $r_{0}: J_{0} \rightarrow \mathbb{Z}_{2}$ for the value assignment defined by $r_{0}(v)=0$ for all $v \in J_{0}$. Let $U$ be a Clifford unitary as described in the statement of the Theorem. We think of $\Phi_{J, r}$ as the composite of two maps:

$$
\Phi_{J, r}(X)=U \Phi_{J_{0}, r_{0}}(X) U^{\dagger}
$$

Part (1) follows from the relation $U \Pi_{J_{0}, r_{0}} U^{\dagger}=\Pi_{J, r}$. Part (2) holds since $U$ acts on $\Lambda_{n}$ by permuting its vertices 9 . Also this action maps a cnc-type vertex to a cnc-type vertex, which implies part (3).

## 4 Reduction of the classical simulation

We now turn to the second question posed in the introduction, namely whether the classical simulation of the update of the composite vertices-whose existence was established in Theorem 2 - under the operations of QCM can be reduced to the classical simulation of their constituent parts. This is indeed the case, as Theorem 3 below demonstrates.
Theorem 3 Any quantum computation in the magic state model (QCM) that operates on an initial state $U\left(X_{A} \otimes\left(\Pi_{\sigma}\right)_{B}\right) U^{\dagger}$, where $X \in \Lambda_{m}$, is an m-qubit vertex and $\Pi_{\sigma}:=|\sigma\rangle\langle\sigma|$ is the projector on an $(n-m)$-qubit stabilizer state $|\sigma\rangle$ and $U$ is an n-qubit Clifford unitary, can be efficiently reduced to a QCM on initial state $X$ alone.
The theorem says that supplementing a vertex $X$ with a stabilizer state does not increase the computational power of QCM. A proof of a similar result is given in Ref. [32, $\S \mathrm{V}$ ] for the case where $X_{A}$ in the statement of Theorem 3 is replaced by the state $|T\rangle\left\langle\left. T\right|^{\otimes m}\right.$.

Proof of Theorem 3. We start from the version of QCM where the quantum computation consists of a sequence of Pauli measurements. All Clifford unitaries can be propagated forward past the last measurement (conjugating the measured observables in the passing), and then discarded. Thus, wlog. we consider initial states of form $\tilde{X}=X_{A} \otimes\left(\Pi_{\sigma}\right)_{B}$.

Let $\mathcal{T}$ denote a finite sequence of Pauli observables on $A \otimes B$. We give an explicit procedure to replace the sequence $\mathcal{T}$ by an equivalent sequence $\tilde{\mathcal{T}}^{(A)}$ of observables that act only on the subsystem $A$. The proof is by induction, and the induction hypothesis is that, at time $t$, the sequence $\mathcal{T}_{\leq t}$ of measurements has been replaced by a computationally equivalent sequence $\tilde{\mathcal{T}}_{\leq t}^{(A)}$ of Pauli measurements on the register $A$ only. This statement is true for $t=0$, i.e., the empty measurement sequence. We now show that the above statement for time $t$ implies the analogous statement for time $t+1$.

At time $t$, the state of the quantum register evolved under the computationally equivalent measurement sequence $\tilde{\mathcal{T}}_{\leq t}^{(A)}$ is $\tilde{Y}(t)=Y(t)_{A} \otimes\left(\Pi_{\sigma}\right)_{B}$. We now consider the Pauli observable $T(t+1) \in \mathcal{T}$ to be measured next, and write $T(t+1)=R_{A}(t+1) \otimes S_{B}(t+1)$. There are two cases:

Case I: $T(t+1)$ commutes with the entire stabilizer $\mathcal{S}$ of $|\sigma\rangle$. Hence, also $S_{B}(t+1)$ commutes with $\mathcal{S}$. But then, either $S_{B}(t+1)$ or $-S_{B}(t+1)$ is in $\mathcal{S}$, and $S_{B}(t+1)$ may be replaced by its eigenvalue $\pm 1$ in the measurement. Hence, the measurement of $T(t+1)$ is equivalent to the measurement of $\pm R_{A}(t+1)$.

Case II: $T(t+1)$ does not commute with the entire stabilizer $\mathcal{S}$ of $|\sigma\rangle$. Then, the measurement outcome $s_{t+1}$ is completely random. Further, there exists a Clifford unitary $V$ such that

$$
V \mathcal{S}(t+1) V^{\dagger}=\left\langle X_{B: 1}, X_{B: 2}, . ., X_{B: m}\right\rangle, \quad V T(t+1) V^{\dagger}=Z_{B: 1}
$$

Therefore, the state resulting from the measurement of $T(t+1)$, with outcome $s_{t+1}$ on the state $\tilde{Y}(t)$ is the same state as the one resulting from the following procedure:

1. Apply the Clifford unitary $V$ to $\tilde{Y}(t)=Y(t)_{A} \otimes\left(\Pi_{\sigma}\right)_{B}$, leading to

$$
V \tilde{Y}(t) V^{\dagger}=Y^{\prime}(t) \otimes|\overline{+}\rangle\left\langle\left.\overline{+}\right|_{B}\right.
$$

where $|\overline{+}\rangle_{B}:=\bigotimes_{i \in B}|+\rangle_{B: i}$.
2. Measure $Z_{B: 1}$ on $Y^{\prime}(t) \otimes|\bar{\mp}\rangle\left\langle\left.\bar{\mp}\right|_{B}\right.$, with outcome $s_{t+1}$.
3. Apply $V^{\dagger}$.

Now, note that the measurement in Step 2, of the Pauli observable $Z_{B: 1}$ is applied to the stabilizer state $|\overline{+}\rangle_{B}$. The result is $\left|\sigma^{\prime}(t+1)\right\rangle=\left|s_{t+1}\right\rangle_{B: 1} \bigotimes_{j=2}^{m}|+\rangle_{B: j}$; that is the first qubit of subsystem $B$ is now in a $Z$-eigenstate, and the other qubits are unchanged. Therefore, after normalization, the effect of the measurement can be replaced by the unitary $\left(X_{B: 1}\right)^{s_{t+1}} H_{B: 1}$.

Thus, the whole procedure may be replaced by the Clifford unitary $V^{\dagger}\left(X_{B: 1}\right)^{s_{t+1}} H_{B: 1} V$. But Clifford unitaries don't need to be implemented. They are just propagated past the last measurement, thereby affecting the measured observables by conjugation whereby their Pauli-ness is preserved. In result, in Case II, the measurement of $T(t+1)$ doesn't need to be performed at all. It is replaced by a coin flip, and efficient classical post-processing of the subsequent measurement sequence.

We conclude that in both the cases I and II, given the induction assumption, the original measurement sequence $\mathcal{T}_{\leq t+1}$ can be replaced by a computationally equivalent measurement sequence $\tilde{\mathcal{T}}_{\leq t+1}^{(A)}$ acting on register $A$ only. By induction, the complete measurement sequence $\mathcal{T}$ can be replaced by a computationally equivalent sequence $\tilde{\mathcal{T}}^{(A)}$ acting on $A$ only.

Since the measurements $\tilde{\mathcal{T}}^{(A)}$ are applied to an unentangled initial state $X_{A} \otimes\left(\Pi_{\sigma}\right)_{B}$, the register $B$ may be dropped without loss of information. Thus, any sequence of Pauli measurements on the initial state $X_{A} \otimes\left(\Pi_{\sigma}\right)_{B}$ is efficiently reduced to a Pauli measurement sequence of at most the same length on $X$ alone.

Discussion. Theorem 3 extends the previously known range of efficient classical simulation of QCM by sampling from the polytopes $\Lambda_{n}$. The prior result is Theorem 3 from 24 . It says that if a quantum state $\rho$ can be represented as a probabilistic linear combination of cnc vertices, and the probability distribution defining this expansion can be efficiently sampled from, then any QCM on $\rho$ can be efficiently classically simulated. Classical simulation of probability distributions over stabilizer states is contained therein as a limiting case.

To apply the above Theorem 3, we define vertex classes

$$
\left.\mathcal{W}_{K}:=\left\{U\left(A_{\alpha} \otimes \Pi_{\sigma}\right) U^{\dagger}\left|A_{\alpha} \in \Lambda_{K},\right| \sigma\right\rangle \in \mathcal{S}_{n-K}, U \in \mathrm{Cl}_{n}, n \geq K\right\}
$$

consisting of a union of certain $n$-qubit vertices for $n \geq K$. Therein, $\Pi_{\sigma}$ is the projector corresponding to a $(n-K)$-qubit stabilizer state $|\sigma\rangle$ and $\mathrm{Cl}_{n}$ is the $n$-qubit Clifford group. Every class $\mathcal{W}_{K}$ contains of vertices on arbitrarily many qubits for $n \geq K$. The present extension of Theorem 3 of [24], based on Theorem 3 above, is the following.
Corollary 1 Consider an $n$-qubit quantum state that can be expanded into a probabilistic linear combination of vertices from the set $\mathcal{W}_{K}$, for a given value of $K$. Then, the computational cost of simulating any QCM on $\rho$ is polynomial in $n$.
Note that the simulation is (likely to be) inefficient in $K$.

## 5 Beyond vertices of cnc-type

In the previous section we established that the complexity of simulating QCM for a composite vertex $U\left(X_{A} \otimes\left(\Pi_{\sigma}\right)_{B}\right) U^{\dagger}$ efficiently reduces to the simulation of QCM on $X_{A}$. But which
vertices $X$ can we actually put explicitly into this reduction?-To date, the only family of vertices which is explicitly described, including the update under Pauli measurements, are the vertices of cnc-type.

For a single qubit, all eight vertices are equivalent under Clifford transformations, and cnc. For two qubits, there are 8 Clifford-equivalence classes of vertices 29, 33, two of which are of cnc-type.

In this section, we give a complete characterization of the update rules under Pauli measurement for one class of two-qubit vertices that are not cnc. A distinguishing feature of the vertices considered is that the expectations $\left\langle T_{v}\right\rangle$ take values in $\{0, \pm 1 / 2, \pm 1\}$ whereas in the cnc case these expectations belong to $\{0, \pm 1\}$.

Specifically, we are concerned with the Clifford orbit of the vertex denoted by $A_{\alpha_{0}}$ whose coordinates in the Pauli basis (i.e. the expectations $\left\langle T_{v}\right\rangle$ ) are given as follows

| $I I$ | $I X$ | $X I$ | $X X$ | $I Z$ | $I Y$ | $X Z$ | $X Y$ | $Z I$ | $Z X$ | $Y I$ | $Y X$ | $Z Z$ | $Z Y$ | $Y Z$ | $Y Y$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $-1 / 2$ | $1 / 2$ | 0 | $-1 / 2$ | $-1 / 2$ | -1 | 0 | $1 / 2$ | -1 | $-1 / 2$ | 0 | 0 | 0 | 0 | 1 |

We know that there are 1920 vertices in this orbit (by computer calculation). The set of vertices in the Clifford orbit of $A_{\alpha_{0}}$ will be denoted by

$$
\begin{equation*}
\mathcal{O}=\left\{U A_{\alpha_{0}} U^{\dagger} \mid U \in \mathrm{Cl}_{n}\right\} \tag{10}
\end{equation*}
$$

For our construction we will consider noncontextual subsets of $E_{2}$ that are not necessarily closed. Let $\Omega$ be a subset of $E_{n}$ and $\gamma: \Omega \rightarrow \mathbb{Z}_{2}$ be a value assignment. Associated to $(\Omega, \gamma)$ we can define the operator $A_{\Omega}^{\gamma}$ as in Eq. (3).

Construction. The vertices in the Clifford orbit $\mathcal{O}$ given in Eq. 10) have the following form

$$
\begin{equation*}
A_{I, \Omega}^{\gamma}=A_{I}^{\gamma}+\frac{1}{4}\left(A_{\Omega}^{\gamma^{\prime}}-A_{\Omega}^{\gamma^{\prime \prime}}\right) \tag{11}
\end{equation*}
$$

where
C. $1 I \subset E_{2}$ is a maximal isotropic subspace.
C. $2 \gamma: I \rightarrow \mathbb{Z}_{2}$ is a value assignment.
C. 3 The set $\Omega$ is constructed from a collection $\mathcal{C}$ described in (C.4) by the following formula

$$
\begin{equation*}
\Omega=E_{2}-\Omega^{\perp} \quad \text { where } \quad \Omega^{\perp}=\left(\bigcup_{J \in \mathcal{C}} J\right)-\{0\} \tag{12}
\end{equation*}
$$

C. 4 The collection $\mathcal{C}=\mathcal{C}(I)$ of maximal isotropics (see Fig. (11)) is defined using the following rules
R. $1 \mathcal{C}$ contains $I$,
R. 2 for each $J \in \mathcal{C}$ and $0 \neq v \in J$ exactly one of the two subspaces $J^{\prime} \in \mathcal{I}\left(E_{2}\right)-\{J\}$ containing $v$ is contained in $\mathcal{C}$.
C. 5 The value assignments $\gamma^{\prime}$ and $\gamma^{\prime \prime}$ on $\Omega$ are uniquely specified by the requirements
V. $1 \gamma^{\prime}(0)=\gamma^{\prime \prime}(0)=0$,
V. $2 \gamma^{\prime}(v)=1+\gamma^{\prime \prime}(v)$ for $v \in \Omega-\{0\}$,
V. $3 \gamma^{\prime}(v)+\gamma^{\prime}(w)+\beta(v, w)=\gamma(v+w)$ for $v, w \in \Omega$ such that $[v, w]=0$ and $v+w \in I$. Note that (V.2) implies that $\gamma^{\prime \prime}$ also satisfies this property.

In summary a vertex in the Clifford orbit $\mathcal{O}$ is specified by $(I, \gamma, \mathcal{C})$. Counting these components: 15 maximal isotropics, $2^{2}$ value assignments, $2^{5}$ collections $\mathcal{C}$ we obtain a total of $1920=15 \times 2^{7}$ vertices. This covers all the vertices in the Clifford orbit of $A_{\alpha_{0}}$.


Fig. 1. The poset of isotropic subspaces of $E_{2}$. Large blue nodes correspond 1-dimensional subspaces and small red nodes correspond to 2-dimensional subspaces. Each node at the boundary repeats 3 times and they are identified. The dark red colored nodes represent the maximal isotropic subspaces in the collection $\mathcal{C}$ corresponding to the vertex $A_{\alpha_{0}}$.

The vertex $A_{\alpha_{0}}$ has the following parameters: $I=\left\langle x_{1}+z_{2}, z_{1}+x_{2}\right\rangle, \mathcal{C}$ consists of the following collection
$\left\{\left\langle x_{1}+z_{2}, z_{1}+x_{2}\right\rangle,\left\langle x_{1}+x_{2}, z_{1}+z_{2}\right\rangle,\left\langle x_{1}+y_{2}, y_{1}+z_{2}\right\rangle,\left\langle z_{1}+y_{2}, y_{1}+x_{2}\right\rangle,\left\langle y_{1}+x_{2}, x_{1}+y_{2}\right\rangle,\left\langle z_{1}+y_{2}, y_{1}+z_{2}\right\rangle\right\}$, and the value assignments are given by

$$
\begin{array}{ccccccccccccccccc} 
& I I & I X & X I & X X & I Z & I Y & X Z & X Y & Z I & Z X & Y I & Y X & Z Z & Z Y & Y Z & Y Y \\
(-1)^{\gamma} & 1 & & & & & & -1 & & & -1 & & & & & & 1 \\
(-1)^{\gamma^{\prime}} & 1 & -1 & 1 & & -1 & -1 & & & 1 & & -1 & & & & & \\
(-1)^{\gamma^{\prime \prime}} & 1 & 1 & -1 & & 1 & 1 & & & -1 & & 1 & & & &
\end{array}
$$

The set $\Omega$ can be calculated from $\mathcal{C}$ using Eq. (12) and it turns out to be $\left\{0, x_{1}, y_{1}, z_{1}, x_{2}, y_{2}, z_{2}\right\}$.
Our strategy for computing the update rules for $A_{I, \Omega}^{\gamma}$ is to consider the update of $A_{I}^{\gamma}$ and $\frac{1}{4}\left(A_{\Omega}^{\gamma^{\prime}}-A_{\Omega}^{\gamma^{\prime \prime}}\right)$ in Eq. 11) separately. First one can be updated using the update rule 24 of cnc-type vertices:

$$
\Pi_{a, s} A_{I}^{\gamma} \Pi_{a, s}=\left\{\begin{array}{cc}
\delta_{s_{a}, \gamma(a)} A_{I}^{\gamma} & a \in I  \tag{13}\\
\frac{1}{2} A_{I \times a}^{\gamma \times a} & a \notin I .
\end{array}\right.
$$

For the second one we first define a cnc set $\tilde{\Omega}$ obtained as the closure of $\Omega \cap\langle a\rangle^{\perp}$ under inference. We also extend $\gamma^{\prime}$ and $\gamma^{\prime \prime}$ on this cnc set in the expected way. The resulting
value assignments are denoted by $\tilde{\gamma}^{\prime}$ and $\tilde{\gamma}^{\prime \prime}$, respectively. Then the update of $\frac{1}{4}\left(A_{\Omega}^{\gamma^{\prime}}-A_{\Omega}^{\gamma^{\prime \prime}}\right)$ coincides with the update of $\frac{1}{4}\left(A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime}}-A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime \prime}}\right)$ by the properties of $\gamma^{\prime}$ and $\gamma^{\prime \prime}$. By construction $\tilde{\Omega}$ is contained in $\langle a\rangle^{\perp}$, in particular it contains $a$. Eq. 13 gives us

$$
\Pi_{a, s} A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime}} \Pi_{a, s}=\delta_{s_{a}, \tilde{\gamma}^{\prime}(a)} A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime}}
$$

Replacing $\tilde{\gamma}^{\prime}$ with $\tilde{\gamma}^{\prime \prime}$ gives the update rule for $A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime \prime}}$. Next we give the update rules for $A_{I, \Omega}^{\gamma}$. The proof of this result is given in Appendix 1.
Theorem 4 The update rules for $A_{I, \Omega}^{\gamma}$ under Pauli measurements consist of the following three cases:

Case I. Suppose that $a \in I$ and $a \notin \Omega$.
(1.a) If $\gamma(a) \neq s$ then $\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}=0$.
(1.b) If $\gamma(a)=s$ then

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{2 A_{\langle a\rangle \perp}^{\tilde{\alpha}_{0}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}_{1}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}_{2}}}{4}
$$

where the value assignments are given in Eq. A.2).
Case II. Suppose that $a \notin I$ and $a \in \Omega$.
(2.a) If $\tilde{\gamma}^{\prime}(a) \neq s$ then

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=A_{\langle a\rangle^{\perp}}^{\tilde{\alpha}^{\prime}}
$$

where the value assignments are given in Eq. A.3).
(2.b) If $\tilde{\gamma}^{\prime}(a)=s$ then

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{2 A_{\langle a\rangle \perp}^{\tilde{\alpha}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}^{\prime}}}{3}
$$

where the value assignments are given in Eq. A.4.
Case III. Suppose that $a \notin I$ and $a \notin \Omega$.
(3.a) If $\tilde{\gamma}^{\prime}(a) \neq s$ then

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{A_{\langle a\rangle \perp}^{\tilde{\alpha}_{0}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}_{1}}}{2}
$$

where the value assignments are given in Eq. A.5.
(3.b) If $\tilde{\gamma}^{\prime}(a)=s$ then

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{A_{\langle a\rangle \perp}^{\tilde{\alpha}_{0}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}_{1}}}{2}
$$

where the value assignments are given in Eq. A.6.

Discussion. Prior to this work the only class of $n$-qubit vertices that is known to give efficient classical simulation was the class of cnc vertices 24. For the efficiency of the simulation each update rule is required to produce a probability distribution which can be efficiently sampled. Our description of the new type of vertices in $\Lambda_{2}$ and their update rules under Pauli measurements allows us to extend this result to a larger class of vertices. Moreover, this is not restricted to $n=2$ case. Theorem 3 implies that the classically efficiently simulable sector of $\Lambda_{n}$ extends with these new classes of vertices. To make this precise (relying on Theorem 2 we enlarge the set of cnc-type vertices by taking the disjoint union of $n$-qubit cnc vertices with the image of the vertices in $\mathcal{O}$ defined in Eq. 10 under the $\Phi$-map:

$$
\mathcal{V}_{n}^{\prime}:=\mathcal{V}_{n}^{\mathrm{cnc}} \sqcup\left\{U\left(A_{\alpha} \otimes \Pi_{\sigma}\right) U^{\dagger} \mid A_{\alpha} \in \mathcal{O}\right\}
$$

where $\Pi_{\sigma}$ is a $(n-2)$-qubit stabilizer projector and $U$ is an $n$-qubit Clifford unitary.
Corollary 2 Consider an n-qubit quantum state $\rho$ that can be expressed as a probabilistic linear combination $p_{\rho}: \mathcal{V}_{n}^{\prime} \rightarrow \mathbb{R}_{\geq 0}$. If $p_{\rho}$ can be efficiently sampled from then the classical simulation of any $Q C M$ on $\rho$ is efficient.

## 6 Conclusion

This paper is an expedition into the state polytopes $\Lambda_{n}, 9,29$, which are presently largely uncharted territory. The study of these polytopes is motived by the fact that they form the structural basis of a hidden-variable description of universal quantum computation 9 .

Here we have shown that certain extremal points of the $\Lambda_{n}$ can be built from "smaller parts", namely a vertex of state polytope $\Lambda_{m}$ on a smaller number $m<n$ of qubits, and a stabilizer state. Further, we have shown that the classical simulation of the evolution of such composite vertices can be reduced to the evolution of their parts. We have also described a new class of vertices outside the known cnc classification, together with their update rules under Pauli measurements.

A possible next question is as follows. The map $\Phi$ takes vertices of $\Lambda_{m}$ to vertices of $\Lambda_{n}$, $n>m$, by tensoring on projectors onto stabilizer states. Are there generalizations of this map that use more general constructs than stabilizer states as parameters of the mapping, and more general notions of composition than the tensor product?

To conclude with a broader comment, the state polytopes $\Lambda_{n}$ are a novel object in the theory of quantum computation and foundations of quantum mechanics. It is presently unknown how easy or hard their study is going to be, and which techniques will be useful. With the present investigation, we have made a first dent into the subject.

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## Appendix A Proof of Theorem 4

As a preparation for the update rules of $A_{I, \Omega}^{\gamma}$ we consider certain linear combinations of operators in Herm(2) and express them as probabilistic mixtures of the vertices of $\Lambda_{1}$. We will denote the vertices in $\Lambda_{1}$ by $A_{E}^{\alpha}$ where $\alpha$ is a value assignment on $E=E_{1}$. Other points in $\Lambda_{1}$ that we are interested in are the projectors $\Pi_{v, s_{v}}$ where $v=x, y, z$, where $y=x+z$, and $s_{v}=0,1$.

Lemma 3 We have the following decompositions for the points in $\Lambda_{1}$. Let $v, w \in E$ be non-zero distinct elements.

1. Let $\alpha_{0}$ and $\alpha_{1}$ be value assignments on $E$ defined by $\alpha_{0}(v)=\alpha_{1}(v)=s_{v}, \alpha_{1}(w)=$ $1+\alpha_{0}(w)$ and $\alpha_{1}(v+w)=1+\alpha_{0}(v+w)$. Then

$$
\Pi_{v, s_{v}}=\frac{A_{E}^{\alpha_{0}}+A_{E}^{\alpha_{1}}}{2}
$$

2. Let $\alpha_{0}$ and $\alpha_{1}$ be value assignments on $E$ defined by $\alpha_{0}(v)=\alpha_{1}(v)=s_{v}, \alpha_{0}(w)=$ $\alpha_{1}(w)=s_{w}$ and $\alpha_{1}(v+w)=1+\alpha_{0}(v+w)$. Then

$$
\Pi_{v, s_{v}}+\frac{\Pi_{w, s_{w}}-\Pi_{w, s_{w}+1}}{2}=\frac{A_{E}^{\alpha_{0}}+A_{E}^{\alpha_{1}}}{2}
$$

3. Let $\alpha^{\prime}$ be value assignment on $E$ defined by $\alpha^{\prime}(v)=\alpha(v), \alpha^{\prime}(w)=1+\alpha(w)$ and $\alpha^{\prime}(v+w)=1+\alpha(v+w)$. Then

$$
\frac{2 \Pi_{v, \alpha(v)}+A_{E}^{\alpha}}{3}=\frac{2 A_{E}^{\alpha}+A_{E}^{\alpha^{\prime}}}{3}
$$

4. Let $\alpha^{\prime}$ be value assignment defined in (3). Then

$$
2 \Pi_{v, \alpha(v)}-A_{E}^{\alpha}=A_{E}^{\alpha^{\prime}}
$$

5. Let $\alpha_{i}, i=0,1,2$, be defined by $\alpha_{i}(v)=s_{v}$ for all $i, \alpha_{0}(w)=\alpha_{1}(w)=1+\alpha_{2}(w)=s_{w}$, $\alpha_{1}(v+w)=\alpha_{2}(v+w)=1+\alpha_{0}(v+w)$. Then

$$
\Pi_{v, s_{v}}+\frac{\Pi_{w, s_{w}}-\Pi_{w, s_{w}+1}}{4}=\frac{2 A_{E}^{\alpha_{0}}+A_{E}^{\alpha_{1}}+A_{E}^{\alpha_{2}}}{4}
$$

Proof of Lemma 3. Verification is straightforward: We write each side of the equations in the Pauli basis and compare.

Let us label the maximal isotropics in $\langle a\rangle^{\perp}$ by $I_{v}=\langle\tilde{v}, a\rangle, I_{w}=\langle\tilde{w}, a\rangle$ and $I_{v+w}=$ $\langle\tilde{v}+\tilde{w}, a\rangle$. We introduce a map

$$
\begin{equation*}
\Lambda_{1} \rightarrow \Lambda_{2} \tag{A.1}
\end{equation*}
$$

determined by $A_{E}^{\alpha} \mapsto A_{\langle a\rangle \perp}^{\tilde{\alpha}}$ where $\tilde{\alpha}$ is specified by $\tilde{\alpha}(a)=s_{a}, \tilde{\alpha}(b)=\alpha(b)$ for $b=\tilde{v}, \tilde{w}, \tilde{v}+\tilde{w}$. In the following proof we label the maximal isotropic subspaces of $\langle a\rangle^{\perp}$ by $I_{v}, I_{w}, I_{v+w}$. Proof of Theorem 4. In Case I we have

$$
\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}=\delta_{s_{a}, \gamma(a)}\left(A_{I}^{\gamma}+\frac{1}{4}\left(A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime}}-A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime \prime}}\right)\right)
$$

where we used $\tilde{\gamma}^{\prime}(a)=\tilde{\gamma}^{\prime \prime}(a)=\gamma(a)$ since $a=v+w$ for some $v, w \in \Omega-\{0\}$. In this case $I$ and $\tilde{\Omega}$ are maximal isotropics in $\langle a\rangle^{\perp}$ intersecting at $\langle a\rangle$. (1.a) follows immediately by calculating $\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}$. For (1.b) we observe that Lemma 3 part (5) and Eq. A.1) imply that

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=A_{I}^{\gamma}+\frac{1}{4}\left(A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime}}-A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime \prime}}\right)=\frac{2 A_{\langle a\rangle \perp}^{\tilde{\alpha}_{0}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}_{1}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}_{2}}}{4}
$$

where $I_{v}=I, I_{w}=\tilde{\Omega}, s_{v}=\gamma(\tilde{v}), s_{w}=\tilde{\gamma}^{\prime}(\tilde{w})$,

$$
\begin{array}{r}
\tilde{\alpha}_{0}(a)=\tilde{\alpha}_{1}(a)=\tilde{\alpha}_{2}(a)=s_{a} \\
\tilde{\alpha}_{0}(\tilde{v})=\tilde{\alpha}_{1}(\tilde{v})=\tilde{\alpha}_{2}(\tilde{v})=\gamma(\tilde{v})  \tag{A.2}\\
\tilde{\alpha}_{0}(\tilde{w})=\tilde{\alpha}_{1}(\tilde{w})=1+\tilde{\alpha}_{2}(\tilde{w})=\tilde{\gamma}^{\prime}(\tilde{w}) \\
1+\tilde{\alpha}_{0}(\tilde{v}+\tilde{w})=\tilde{\alpha}_{1}(\tilde{v}+\tilde{w})=\tilde{\alpha}_{2}(\tilde{v}+\tilde{w}) .
\end{array}
$$

Case II follows from

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{1}{2} A_{I \times a}^{\gamma \times a}+\frac{1}{4}\left(\delta_{s_{a}, \tilde{\gamma}^{\prime}(a)} A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime}}-\delta_{s_{a}, 1+\tilde{\gamma}^{\prime}(a)} A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime \prime}}\right)
$$

since $\tilde{\gamma}^{\prime \prime}(v)=\tilde{\gamma}^{\prime}(v)+1$ for $v \in \Omega-\{0\}$. Here $\tilde{\Omega}=\langle a\rangle^{\perp}$. For (2.a) Lemma 3 part (4) and Eq. A.1) imply that

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{1}{2} A_{I \times a}^{\gamma \times a}-\frac{1}{4} A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime \prime}}=A_{\langle a\rangle}^{\tilde{\alpha}^{\prime}}
$$

where $I_{v}=I \times a, I_{w}$ is one of the other two isotropics,

$$
\begin{array}{r}
\tilde{\alpha}^{\prime}(a)=s_{a} \\
\tilde{\alpha}^{\prime}(\tilde{v})=\tilde{\gamma}^{\prime \prime}(\tilde{v}) \\
\tilde{\alpha}^{\prime}(\tilde{w})=1+\tilde{\gamma}^{\prime \prime}(\tilde{w})  \tag{A.3}\\
\tilde{\alpha}^{\prime}(\tilde{v}+\tilde{w})=1+\tilde{\gamma}^{\prime \prime}(\tilde{v}+\tilde{w}) .
\end{array}
$$

For (2.a) Lemma 3 part (4) and Eq. A.1 imply that

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{1}{2} A_{I \times a}^{\gamma \times a}+\frac{1}{4} A_{\tilde{\Omega}}^{\tilde{\tilde{\gamma}}^{\prime}}=\frac{2 A_{\langle a\rangle \perp}^{\tilde{\alpha}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}^{\prime}}}{3}
$$

where $I_{v}=I \times a, I_{w}$ is one of the other two isotropics, $\tilde{\alpha}=\tilde{\gamma}^{\prime}$,

$$
\begin{array}{r}
\tilde{\alpha}^{\prime}(a)=s_{a} \\
\tilde{\alpha}^{\prime}(\tilde{v})=\tilde{\gamma}^{\prime}(\tilde{v})  \tag{A.4}\\
\tilde{\alpha}^{\prime}(\tilde{w})=1+\tilde{\gamma}^{\prime}(\tilde{w}) \\
\tilde{\alpha}^{\prime}(\tilde{v}+\tilde{w})=1+\tilde{\gamma}^{\prime}(\tilde{v}+\tilde{w})
\end{array}
$$

Case III follows from the following computation

$$
\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}=\frac{1}{2} A_{I \times a}^{\gamma \times a}+\frac{\delta_{s_{a}}, \tilde{\gamma}^{\prime}(a)}{4}\left(A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime}}-A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime \prime}}\right)
$$

We have $\tilde{\gamma}^{\prime}(a)=\tilde{\gamma}^{\prime \prime}(a)$ since $a$ can be written as $a=v+w$ with $v, w \in \Omega-\{0\}$. In this case $I$ and $\tilde{\Omega}$ are maximal isotropics contained in $\langle a\rangle^{\perp}$ intersecting at $\langle a\rangle$. For (3.a) Lemma 3 part (1) and Eq. A.1 imply that

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{1}{2} A_{I \times a}^{\gamma \times a}=\frac{A_{\langle a\rangle \perp}^{\tilde{\alpha}_{0}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}_{1}}}{2}
$$

where $I_{v}=I \times a, I_{w}=\tilde{\Omega}, s_{v}=\gamma(\tilde{v})$,

$$
\begin{array}{r}
\tilde{\alpha}_{0}(a)=\tilde{\alpha}_{1}(a)=s_{a} \\
\tilde{\alpha}_{0}(\tilde{v})=\tilde{\alpha}_{1}(\tilde{v})=\gamma(\tilde{v}) \\
\tilde{\alpha}_{1}(\tilde{w})=1+\tilde{\alpha}_{0}(\tilde{w})  \tag{A.5}\\
\alpha_{1}(\tilde{v}+\tilde{w})=1+\tilde{\alpha}_{0}(\tilde{v}+\tilde{w})
\end{array}
$$

For (3.b) Lemma 3 part (2) and Eq. A.1 imply that

$$
\frac{\Pi_{a, s} A_{I, \Omega}^{\gamma} \Pi_{a, s}}{\operatorname{Tr}\left(A_{I, \Omega}^{\gamma} \Pi_{a, s}\right)}=\frac{1}{2} A_{I \times a}^{\gamma \times a}+\frac{1}{4}\left(A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime}}-A_{\tilde{\Omega}}^{\tilde{\gamma}^{\prime \prime}}\right)=\frac{A_{\langle a\rangle \perp}^{\tilde{\alpha}_{0}}+A_{\langle a\rangle \perp}^{\tilde{\alpha}_{1}}}{2}
$$

where $I_{v}=I \times a, I_{w}=\tilde{\Omega}, s_{v}=\gamma(\tilde{v}), s_{w}=\tilde{\gamma}^{\prime}(\tilde{w})$,

$$
\begin{array}{r}
\tilde{\alpha}_{0}(a)=\tilde{\alpha}_{1}(a)=s_{a} \\
\tilde{\alpha}_{0}(\tilde{v})=\tilde{\alpha}_{1}(\tilde{v})=\gamma(\tilde{v}) \\
\tilde{\alpha}_{0}(\tilde{w})=\tilde{\alpha}_{1}(\tilde{w})=\tilde{\gamma}^{\prime}(\tilde{w})  \tag{A.6}\\
1+\tilde{\alpha}_{0}(\tilde{v}+\tilde{w})=\tilde{\alpha}_{1}(\tilde{v}+\tilde{w}) .
\end{array}
$$

Note that the case where $a \in I$ and $a \in \Omega$ does not occur since $I \cap \Omega=0$.

